

Pictures at SERE 2014

Day 3 (July 2)



S O F I T
L U X U R Y H O

EXIT



Dr. Katerina Gooska
Popstojanova
Vice President Director

SOFIT
LUXURY HOTEL



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DEFENSE RESEARCH AND DEVELOPMENT CANADA
Mr. Philippe Charland
Defense Research and Development Canada















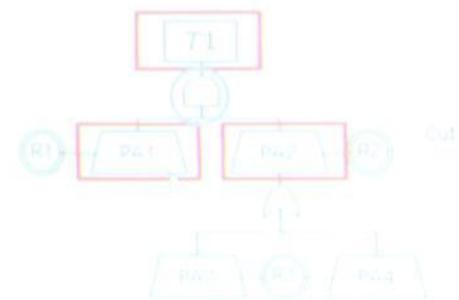






Collision analysis pro

- Step 3: Identification of C
- Cut set
 - The combination of coexist
 - (A set of minimal leaf nodes
 - We applied MOCUS algorit
- Purpose of identifying Cut
 - Analyze whether the action
 - device or not







Quantitative Analysis

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graph TD; A[Design Safety Model] --> B[Failure Mode Analysis]; B --> C[Failure Cause Analysis]; C --> D[Failure Effect and Severity Analysis]; D --> E[Casualty Analysis]; E --> F[FMECA Check List];
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- The most probable causes for each failure mode should be identified and described in FMEA property of error model
 - SAE J1709 provides a list of failure causes for failure modes
 - SAE J1709 suggests that failure causes may be identified by consulting the opinion of experts



Task's schedulability and supply simulation relation

Definition 3. A task $T \in \mathbf{T}^*$ is schedulable by supply $S \in \mathbf{S}^*$ if whenever $T \parallel S \Rightarrow P$ then (i) $P \rightarrow$ and (ii) for all $P \xrightarrow{\alpha} R$ we have $\alpha^{\beta} \cap R = \emptyset$.

Definition 4. A relation $\mathcal{S} \subseteq \mathbf{T}^* \times \mathbf{S}^*$ is a supply simulation relation if for all $(T, S) \in \mathcal{S}$, $S \rightarrow$, and if $S \xrightarrow{\alpha} S'$ then

1. there exists $T \xrightarrow{\beta} T'$ with $\text{sat}(\beta, \alpha)$ and $(T', S') \in \mathcal{S}$, and
2. for any ρ , if $T \xrightarrow{\rho} T'$ and $\rho \preceq \alpha$, then $(T', S') \in \mathcal{S}$.

If there exists a supply simulation relation between T and S , then we write $S \models T$.

Lemma 1. A task $T \in \mathbf{T}^*$ is schedulable by supply $S \in \mathbf{S}^*$ if and only if $S \models T$.



Philippe, A., Lee, I., Sokolsky, O. "PADS: An Approach to Modeling Resource Demand and Supply for the Formal Analysis of Hierarchical Scheduling." *Theoretical Computer Science*, 413(1): 2-20 (2012)



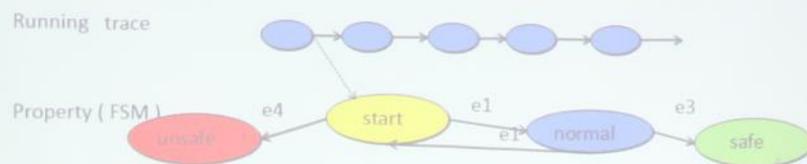
Background

- Cyber-Physical System (CPS) in Many Key Areas: energy, transportation, aviation, etc.
 - Complex: open, large scale, multi-components
 - High Reliability Requirements



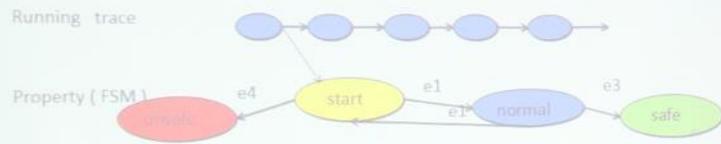
Background

- Runtime Verification: monitors a system to checking whether the running traces meet critical temporal properties
 - Reliability: properties constrain the system
 - Light weight: avoid system model and state explosion
 - Online: verify with the contexts



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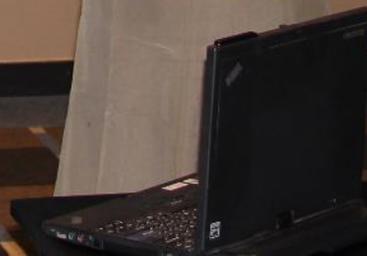




NORTHWESTERN POLYTECHNICAL UNIVERSITY

A Load Scheduling Strategy for Electric Vehicles Charging System

Zheng Wang, Xiao Wu, Hongbin Zhao
San Francisco
2 July 2014





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